

DAFTAR PUSTAKA

- [1] Waldy, Ibnu. 2014. Rancang Bangun Sistem Automatic Guided Vehicle (Agv) Menggunakan RFID untuk Informasi Posisi. Bandung: Telkom University
- [2] Datasheet Arduino Mega 2560
- [3] Datasheet Atmega 8535
- [4] Priyono, Agung. 2014. Perancangan dan Implementasi One Steered Traction Wheel Robot dengan Circular Line Sensor menggunakan Kontrol Logika Fuzzy. Bandung: Telkom University
- [5] Wikipediawan.(2014), Motor Stepper,
<http://id.wikipedia.org/wiki/Potensiometer>
- [6] Fahmizal. 2010,Merancang Rangkaian Sensor Garis,
<https://fahmizaleeits.wordpress.com/tag/cara-kerja-sensor-garis/>
- [7] Baharuddin M. Zafri.Analyst of Line Sensor Configuration for Advanced Line Follower Robot.University Tenaga Nasional, http://www.robot.t.u-tokyo.ac.jp/members/jeffrey/files/SCOREd_2005_ALF.pdf