## **DAFTAR PUSTAKA**

- [1] Basta, Peter O. 2012. *Master's Thesis*: *Quadcopter Flight*. California State University, Northridge.
- [2] DeWitt, Michael., Gee, Seth., Kirkpatrick, Brandon., & Ward, Devitt. 2011. *Multi-Agent System of Quadcopter*, EE464 Senior Design Project. Electrical and Computer Engineering Department University of Texas, Austin.
- [3] Hoffmann, G. & Huang, H. Quadrotor Helicopter Flight Dynamics and Control: Theory and Experiment, 2007.
- [4] Luukkonen, Teppo. 2011. *Modelling and Control of Quadcopter*. School of Science, Aalto University.
- [5] Malgoza, David., Mercedes, Engers F Davance., Smith, Stephen., & West, Joshua. *Quadcopter*. School of Electrical Engineering and Computer Science, University of Central Florida, Orlando, Florida.
- [6] Pascucci, Carlo Alberto.2010. Design, Construction and Model Predictive Control of a Quadcopter Autonomous Aerial Vehicle. Università degli Studi di Siena Facoltà di Ingegneria.
- [7] Vechian, Mongkhun Qetkeaw A.L. 2012. Wireless Control Quadcopter With Stereo Camera and Self-Balancing System. Dissertation Faculty of Electrical and Electronics Engineering Universiti Tun Hussein Onn Malaysia.