

## DAFTAR PUSTAKA

- [1] A. Wirjaputra, ““ Google Autonomous Car ,”” 2012.
- [2] R. R. Kautsar, B. S. B. D, and A. R. A. B. S, “Pengendalian Posisi Mobile Robot Menggunakan Metode Neural Network Dengan Umpan Balik Kamera Pemosisian Global,” *Electron. Eng. Polytecnic Inst. Surabaya (EEPIS)*, ISBN 978-979-8689-14-7, no. Ies, p. 5, 2011.
- [3] F. FAHMIZAL, B. B. MURTI, D. B. PRATAMA, and A. MAYUB, “Kendali Logika Fuzzy pada Car Like Mobile Robot (CLMR) Penjejak Garis,” *ELKOMIKA J. Tek. Energi Elektr. Tek. Telekomun. Tek. Elektron.*, vol. 6, no. 3, p. 451, 2018.
- [4] J. Angeles, *Fundamentals of Robotic Mechanical Systems: Theory, Methods, and Algorithms*. 2003.
- [5] A. Mz, “Pulse Width Modulation ( PWM ),” *Inst. Pertan. Bogor*, pp. 1–4, 2015.
- [6] Sudradjat, “Dasar-Dasar Fuzzy Logic,” *Media Stat.*, vol. 1, no. 1, 2012.
- [7] C. Mathworks, *Fuzzy Logic Toolbox™ User ’ s Guide R 2015 b*. 2015.
- [8] M. A. Sotelo, “Lateral control strategy for autonomous steering of Ackerman-like vehicles,” *Rob. Auton. Syst.*, vol. 45, no. 3–4, pp. 223–233, 2003.