

## DAFTAR PUSTAKA

- [1] “The Raptor Hand, web page.,” [Online]. Available: <http://enablingthefuture.org>
- [2] Thesis, Dual-Arm Robotic Manipulation under Uncertainties and TaskBased Redundancy. 2019.
- [3] C. Park and K. Park, “Design and kinematics analysis of dual arm robot manipulator for precision assembly,” IEEE Int. Conf. Ind. Informatics, pp. 430–435, 2008, doi: 10.1109/INDIN.2008.4618138.
- [4] D.Thesis, Dual-Arm Robotic Manipulation under Uncertainties and Task-Based Redundancy. 2019
- [5] Setiawan, Ari, “Perancangan Lengan Robot Pneumatik Pemindah Plat Menggunakan Programmable Logic Controller”, Penelitian Jurusan Teknik Elektro Universitas Diponegoro, 2004.
- [6] P. Ghassemi, M. Masouleh dan A. Kalhor, “Push recovery for nao humanoid robot,” Robotics and Mechatronics (ICRoM), p. 035–040, 2014.
- [7] D. Kho, “Pengertian dan Fungsi Potensiometer,” Teknik Elektronika, [Online]. Available: <https://www.teknikelektronika.com/pengertian-fungsi-potensiometer/>. [Accessed 13 Agustus 2023].
- [8] “MG996R,” Tower Pro, [Online]. Available: <http://www.towerpro.com.tw/product/mg996r/> . [Accessed 13 Agustus 2023].
- [9] E. W. Pamungkas, “IMPLEMENTASI TELEOPERASI ROBOT DAN TELEKOMUNIKASI VIDEO MENGGUNAKAN SMARTPHONE ANDROID BERBASIS BLUETOOTH.,” vol. I, no. 2, pp. 1-10, 2015.
- [10] M. S. E. S. Sumardi, “PENGENDALIAN LENGAN ROBOT PNEUMATIK PEMINDAH PLAT MELALUI BLUETOOTH DENGAN HANDPHONE BERTEKNOLOGI JAVA,” 2007.

- [11] Dicoding, [Online]. Available: <https://www.dicoding.com/blog/apa-itu-firebase-pengertian-jenis-jenis-dan-fungsi-kegunaannya/>. [Accessed 2 Agustus 2023].
- [12] J. Lafaye, C. Lafaye dan P. B. Wieber, “Model predictive control for tilt recovery of an omnidirectional wheeled humanoid robot,” *Robotics and Automation (ICRA)*, p. 5134–5139, 2015.
- [13] Supendar, “IMPLEMENTASI REMOTE SITE PADA VIRTUAL PRIVATE NETWORK BERBASIS MIKROTIK,” vol. III, no. 1, pp. 85-96, 2016.
- [14] L. I. Y. A. Jordy Lasmana Putra, “PENERAPAN SISTEM KEAMANAN JARINGAN MENGGUNAKAN,” vol. III, no. 2, pp. 260-267, 2018.
- [15] S. J. Sokop, D. J. Mamahit, and S. Sompie, “Trainer Periferal Antarmuka Berbasis Mikrokontroler Arduino Uno,” *J. Tek. Elektro dan Komput.*, vol. 5, no. 3, pp. 13–23, 2016.
- [16] Iswanto, *Motor Servo*, no. September. 2011. [Online]. Available: <http://zoniaelektro.net/motor-servo/>. Accessed [1 Juni 2023]