

TABLE OF CONTENTS

APPROVAL SHEET	ii
ORIGINALITY STATEMENT SHEET	iii
FOREWORD	iv
ACKNOWLEDGEMENTS	v
ABSTRACT.....	vi
TABLE OF CONTENTS.....	vii
LIST OF FIGURES	ix
LIST OF TABLES	x
CHAPTER I INTRODUCTION	1
1.1. Background	1
1.2. Problem Statement	3
1.3. Purpose	3
1.4. Benefits of Research.....	3
1.5. Constraint	3
1.6. Research Method.....	4
1.7. User Projections	4
1.8. Implementation Schedule	5
CHAPTER II LITERATURE REVIEW.....	6
2.1 Autonomous Underwater Vehicles (AUV).....	6
2.2 Control Systems	7
2.3 Proportional Integral Derivative (PID)	10
2.4 Weight.....	12
2.5 Buoyancy and Buoyancy Engine	12
2.6 Drag.....	14
2.7 Pressure	15
CHAPTER III SYSTEM DESIGN	17
3.1. System Overview	17
3.1.1. Block Diagram.....	18
3.1.2. Function and Feature	20
3.2. Hardware Design.....	21

3.2.1. Component Specification.....	24
3.3. Software Design	25
3.3.1. Subsystem Specification	27
CHAPTER IV RESULT AND ANALYSIS.....	28
4.1. Experiment Results.....	28
4.1.1. Motor Position PID Testing and Calibration	28
4.1.2. Pressure Sensor Testing and Calibration	31
4.1.3. Submersible Depth Position PID Testing and Calibration	36
CHAPTER V CLOSING	51
5.1 Conclusion	51
5.2 Recommendations	51
BIBLIOGRAPHY	52
APPENDIX.....	55